#### Extrapolating Learning Curves of Deep Neural Networks Tobias Domhan, Jost Tobias Springenberg, Frank Hutter Freiburg University {domhant,springj,fh}@informatik.uni-freiburg.de Learning curves Random subset of learning curves: Experiments Example extrapolation: 200 250 300 150 epochs Example of model being misled by unusual shape of the learning curve: Extrapolation **Problem definition** Given data points $y_{1:n}$ we would to like to **forecast the future** performance y<sub>last</sub> probabilistically Ouglity of prodiction $y_{last}$ is evaluated at $x_{last}$ , the maximum number of epochs; set to **300 epochs** • *y<sub>last</sub>* in/over/under 90% interval: $y_{last}$ test train Approach Selected k = 10 parametric model families that roughly match learning curves' shape (typically increasing, saturating functions) Model tends to be overconfident based on little data, but rarely pow<sub>3</sub>: $c - a x^{-\alpha}$ $pow_{4}: c - (a x + b)^{-\alpha}$ underpredict Simulated early stopping in optimization $Exp_4: c - e^{-ax^{\alpha}+b}$ Janoschek: $a - (a - \beta)e^{-kx^{\circ}}$ **TPE** (Tree Parzen Estimator) is Replayed all 800 runs based on Gaussian Mixture Models. DR-hill: $\frac{t x^{\eta}}{\kappa^{\eta} + x^{\eta}}$ MMF: $\alpha - \frac{\alpha - \beta}{1 + (\kappa x)^{\delta}}$ Stopped a run when probability of improving over current best got Supports conditional, continuous and discrete parameters and also too small: $P(y_{last} \ge y_{best} \mid y_{1:n}) < 1\%$ priors over them. vap: $e^{(a+\frac{b}{x}+c \log x)}$ loglog linear: log(a log(x) + b)[Bergstra, Bardenet, Bengio, and Kégl, 2011] ۳<u></u> 0.5 $\operatorname{ilog}_2$ : $c - \frac{a}{\log x}$ Weibull: $\alpha - (\alpha - \beta) e^{-(\kappa x)^{\delta}}$ early stopping $\log x$ no early stopping Representative power increased by **convex combination of individual** 2000 3000 1000 4000 models: simulated time(cumulative epochs) **Reached the same accuracy** $f(x) = \sum_{i=1}^{k} w_i f_i(x|\boldsymbol{\theta}_i) + \epsilon$ with $\epsilon \sim N(0, \sigma^2)$ and $\sum_{i=1}^{k} w_i = 1$ 2.7-fold speedup Model uncertainty captured by **MCMC** The prior encoded monotonicity assumption of each of the models We obtained S = 100000 samples from 100 parallel chains of length Ongoing/Future Work 1500 with a burn-in of 500 • Let $\boldsymbol{\xi}$ be the model's parameters $(w_1, \dots, w_k, \boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_k, \sigma^2)$ • Use early stopping in model search

## ... in 30 sec

- **Deep networks** critically depend on **hyperparameters**, but training is **expensive**
- To automate a heuristic that experts use, we built a probabilistic model to forecast the asymptotic accuracy of a given parameter setting and stop all but the most promising runs
- Simulation resulted in a **2.7-fold reduction of overall runtime**

# Motivation

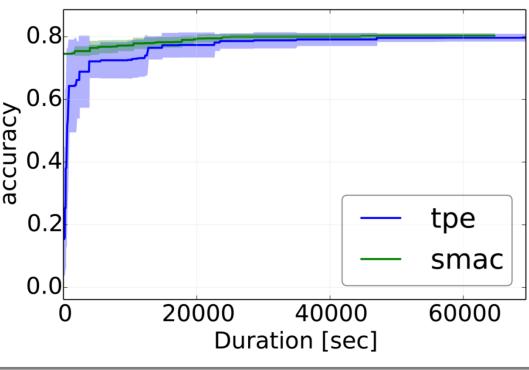
- It takes very few SGD iterations for a human expert to tell good from bad parameter settings
- Yet in hyperparameter optimization every setting is run to the very end
- Automating the prediction of performance **could save a lot of time** and **speed up preliminary evaluations** during development

# Model Search

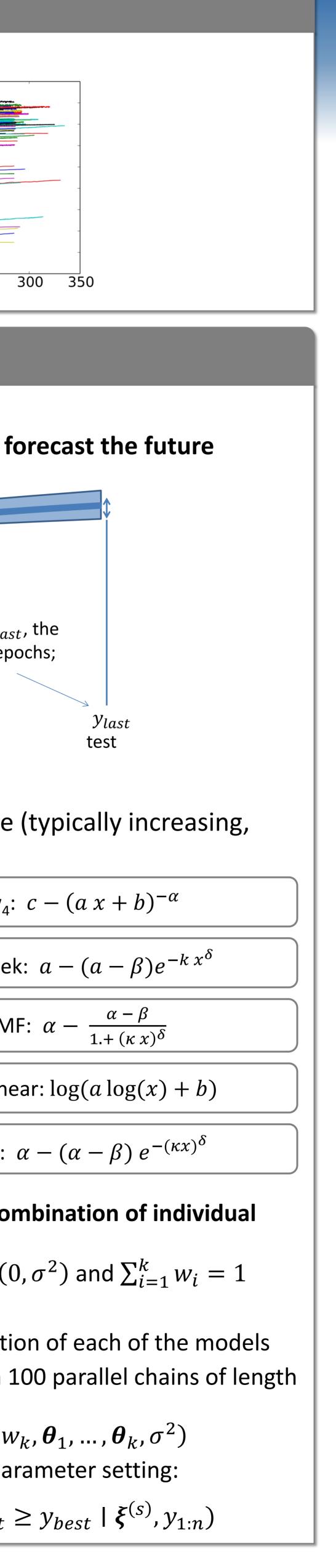
- Search over structure and hyperparameters of deep networks:
  - **81 parameters in total**, namely 9 network parameters and 12 parameters for each of up to 6 layers
  - Neural network software: Caffe [Jia 2013]
- Bayesian optimization methods:

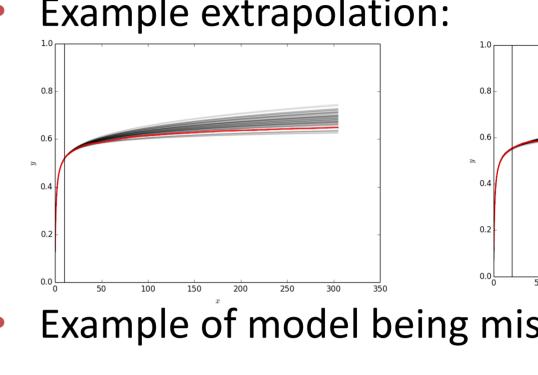
**SMAC** (Sequential Model-based algorithm configuration) is based on random forests and can handle continuous, discrete and conditional hyperparameters. [Hutter, Hoos, and Leyton-Brown, 2011]

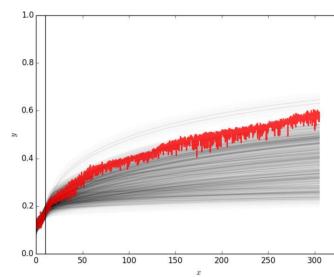
- 5 runs of both SMAC and TPE
- Evaluated a total of **800 networks**
- Dataset: k-means features extracted from CIFAR10 [Krizhevsky 2009; Coates 2011]

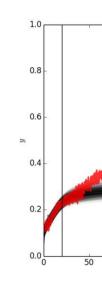


- Probability of improving over current best parameter setting:
- $P(y_{last} \ge y_{best} \mid y_{1:n}) \approx \frac{1}{S} \sum_{s=1}^{S} P(y_{last} \ge y_{best} \mid \xi^{(s)}, y_{1:n})$





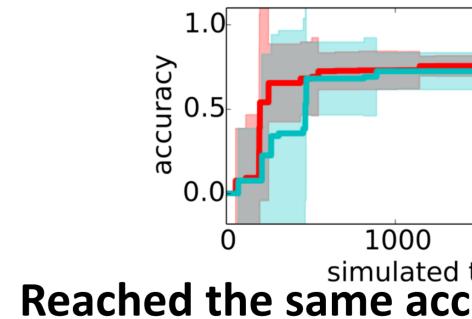




Luality of pi	redictions:								
• RMSE of residual $E[y_m] - y_{last}$ :									
train	10%	30%	50%	70%	90%				
	0.000	0.040	0.020	0.010	0.011				

Quality of predictions:							
• RMSE of residual $E[y_m] - y_{last}$ :							
% train	10%	30%	50%	70%	90%		
RMSE	0.082	0.046	0.026	0.010	0.011		
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% train	10%	30%	50%	70%	90%
y <sub>last</sub> in	42.54 %	48.51%	61.94 %	80.45 %	91.04 %
y <sub>last</sub> over	12.69 %	9.70 %	8.96 %	6.77 %	6.72%
y <sub>last</sub> under	44.77 %	41.79 %	29.10 %	12.78 %	2.24 %



### Control early stopping via Bayesian optimization

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100	150 a	200	250	300	350	

