

Differential Evolution for Neural Architecture Search

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Summary

Contributions

- Standardizing and benchmarking differential evolution (DE) as a *search strategy* for neural architecture search (NAS).
- We demonstrate that our DE yields state-of-the-art performance for NAS, comparing favorably to regularized evolution (RE) and Bayesian optimization.

Observations

- DE yields improved and more robust results for 13 tabular NAS benchmarks based on NAS-Bench-101, NAS-Bench1Shot1, NAS-Bench-201 and NAS-HPO bench.
- DE shows strong *final performance*, compared to RE, BOHB.
- DE appears to be robust to high-dimensional spaces and handle mixed-data types adeptly.

Canonical DE

DE is an evolutionary algorithm that is based on four steps:

- Initialization:** Initialize a population space of NP individuals
 $pop_g = (X_{i,g}^1, X_{i,g}^2, \dots, X_{i,g}^D), i = 1, 2, \dots, NP$

- Mutation:** A new child/offspring is produced
 $V_{i,g} = X_{r1,g} + F \cdot (X_{r2,g} - X_{r3,g})$

- Crossover:** Combine target and mutant to generate a trial

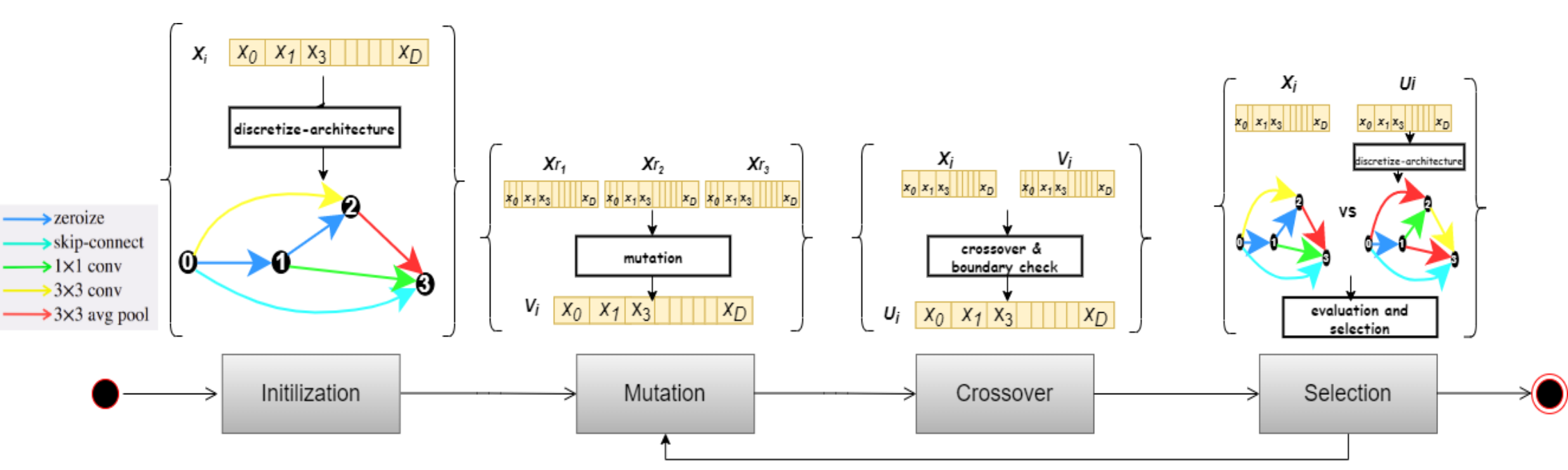
$$u_{i,g}^j = \begin{cases} v_{i,g}^j & \text{if } (rand < Cr) \text{ or } (j = j_{rand}) \\ x_{i,g}^j & \text{otherwise} \end{cases}$$

- Selection:** Evaluates trial and compares to keep or discard

$$X_{i,g} = \begin{cases} U_{i,g} & \text{if } (f(U_{i,g}) \leq f(X_{i,g})) \\ X_{i,g} & \text{otherwise} \end{cases}$$

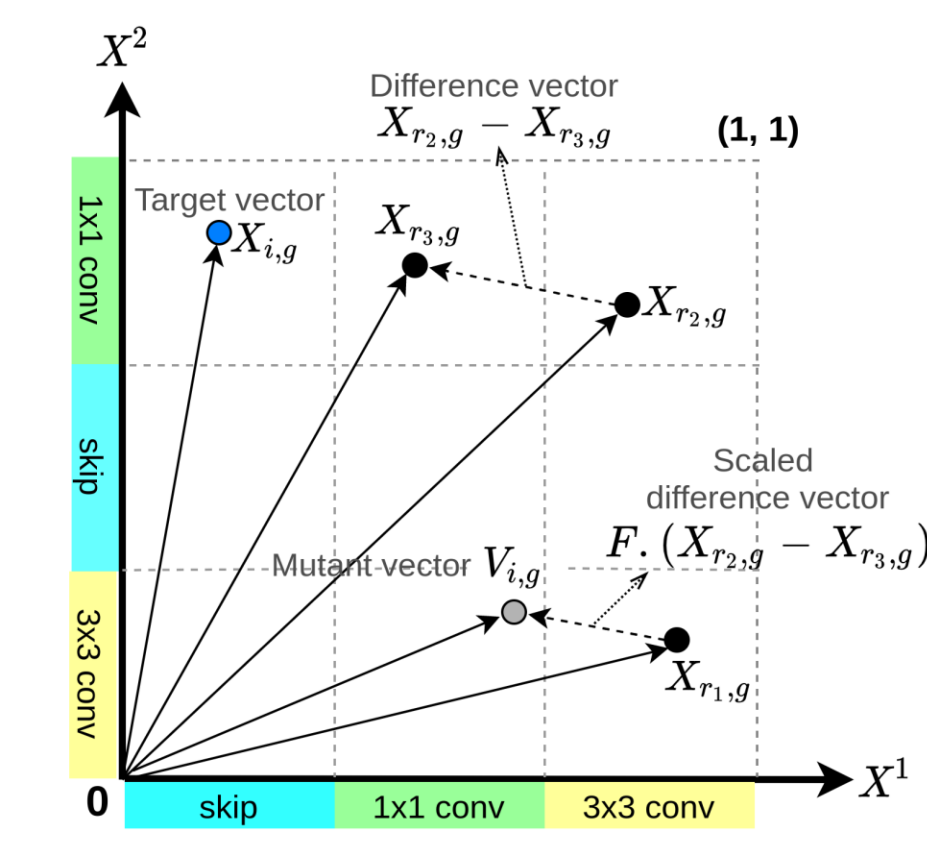
DE for NAS

- The figure below shows the general framework of our DE implementation for NAS.
- We scale all NAS parameters to $[0, 1]$ to let DE work on individuals from a uniform, continuous space.
- We found the best way of applying DE when parameters are discrete or categorical is to keep the population in a continuous space, perform canonical DE, and only discretize copies of individuals to evaluate them.
- The mutation strategy selected was *rand1* and *binomial* crossover were selected as the DE strategies for this work.

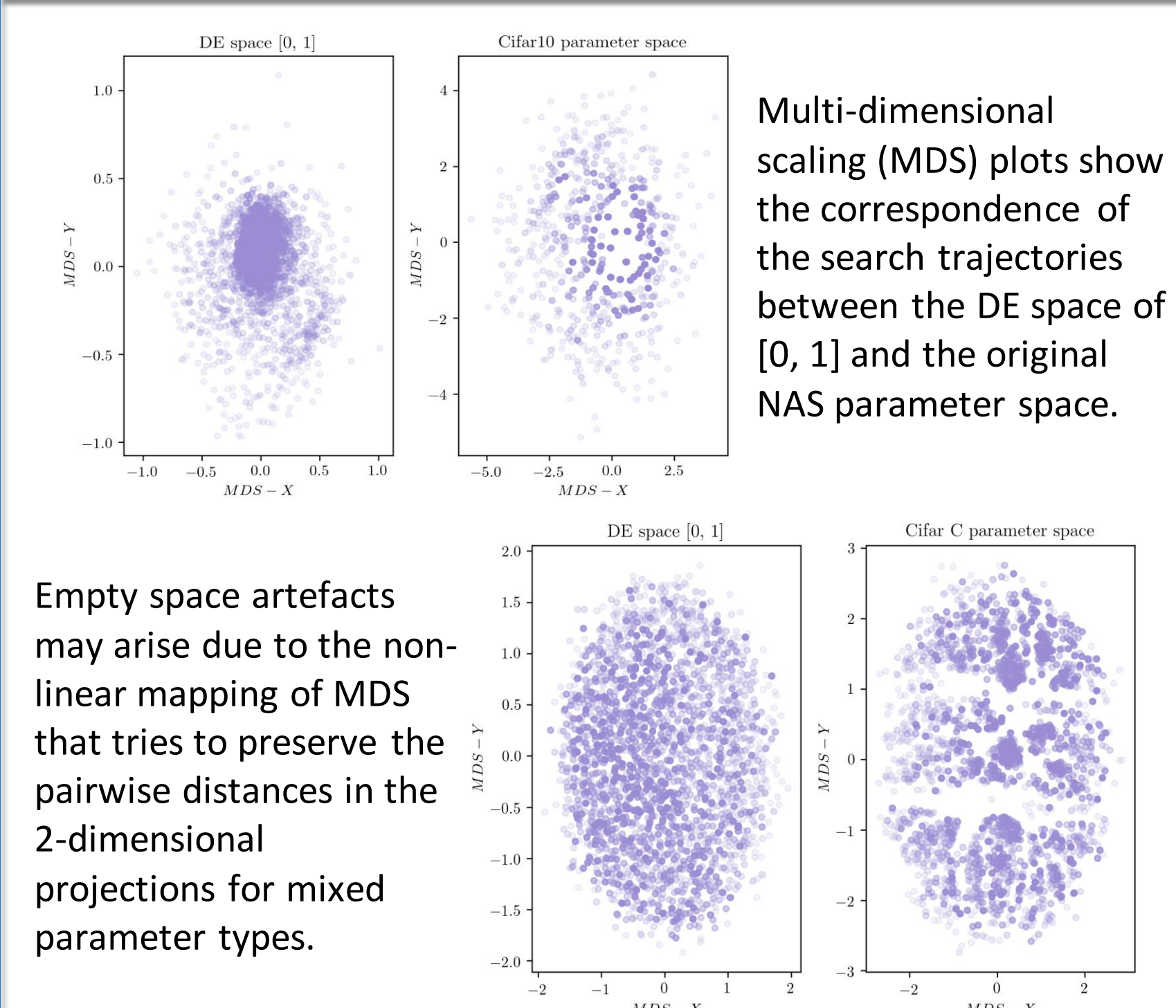


Parameter space mapping

- Integer and float parameters:** $X_i \in [a_i, b_i]$ are retrieved as: $a_i + (b_i - a_i) \cdot U_{i,g}$, where the integer parameters are additionally rounded.
- Ordinal and categorical parameters** $X_i \in \{x_1, \dots, x_n\}$: the range $[0, 1]$ is divided uniformly into n bins.

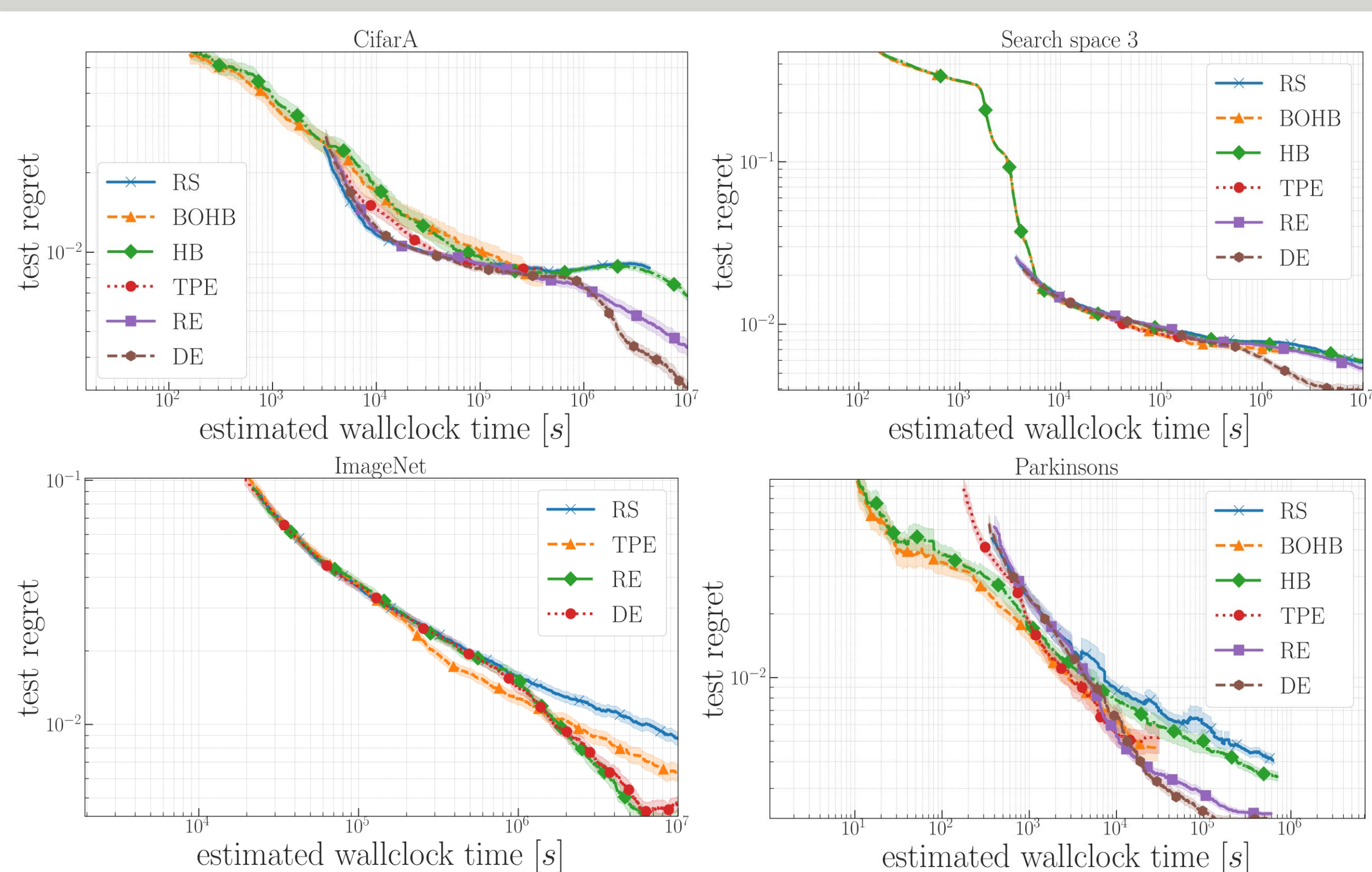


Search space visualization



Experiments

Benchmark Results



NAS-Bench-101			
	CifarA	CifarB	CifarC
BOHB	0.0649 ± 0.00703	0.0648 ± 0.00203	0.065 ± 0.0023
RE	0.0612 ± 0.00342	0.0613 ± 0.00321	0.0637 ± 0.00378
DE	0.0598 ± 0.00262	0.0611 ± 0.00225	0.0606 ± 0.00248

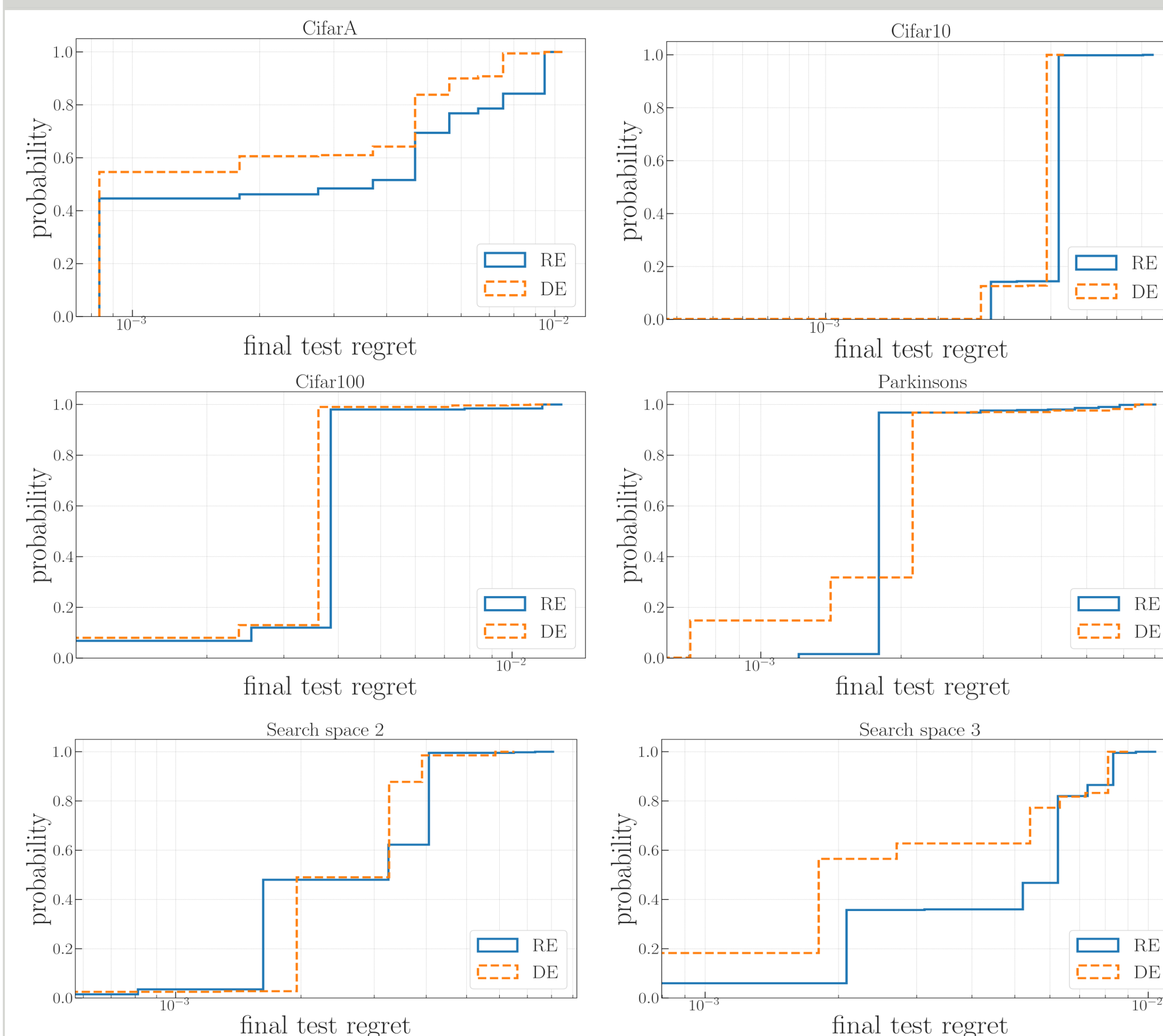
NAS-Bench-1Shot1			
	Search space 1	Search space 2	Search space 3
BOHB	0.0599 ± 0.00271	0.0606 ± 0.00215	0.0602 ± 0.00213
RE	0.0566 ± 0.00076	0.0607 ± 0.00122	0.0588 ± 0.00261
DE	0.0569 ± 0.00097	0.0605 ± 0.00113	0.0573 ± 0.00303

NAS-HPO				
	Protein	Slice	Naval	Parkinsons
BOHB	0.2208 ± 0.00446	0.00019 ± 6.82e-05	5.73e-05 ± 2.3e-04	0.0089 ± 0.00685
RE	0.2155 ± 0.00028	0.00016 ± 2.06e-06	3.59e-05 ± 5.62e-06	0.0065 ± 0.00056
DE	0.2156 ± 0.00048	0.00016 ± 3.54e-06	3.58e-05 ± 3.81e-06	0.0064 ± 0.00078

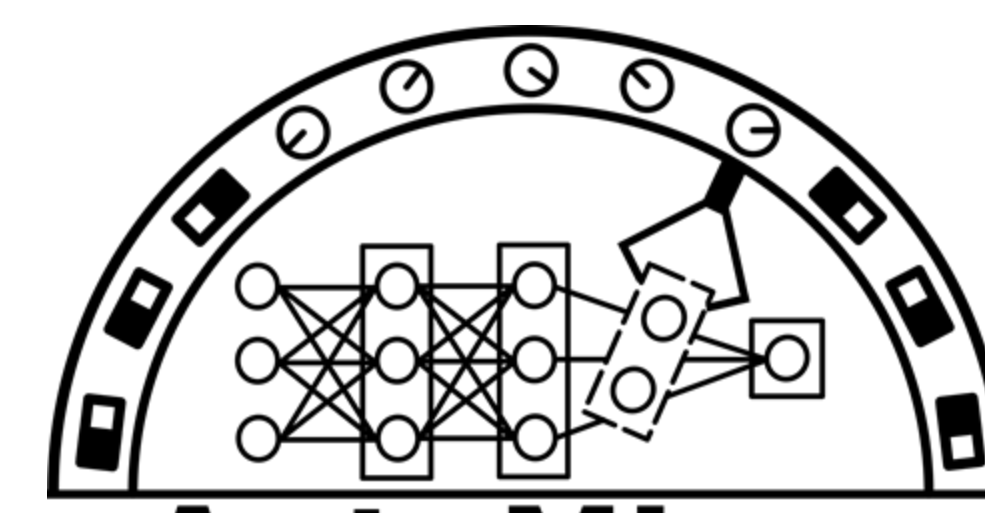
For NAS-101: DE is able to exploit high-dimensional spaces well and handle mixed-types better.

For NAS-1shot1: For search space 3, the most complex, largest space, DE performs best and converges fastest.

Robustness



- For NAS-Bench-101, DE is robust in solving CifarA and CifarC while RE is better in solving CifarB.
- For NAS-Bench-1Shot1, DE is more robust to solve the three search spaces while we can say that RE is competitive in search space 2.
- For NAS-201, RE is more robust than DE in ImageNet while DE is competitively robust to RE in Cifar10 and Cifar100.
- For NAS-HPO, DE shows more robust performance in Slice and Parkinsons datasets. For Protein and Naval datasets, DE is competitively robust to RE.



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Implementation Publicly Available: <https://github.com/automl/DE-NAS>